

Claims: I claim:

- gpc1
1. A massage and tactile stimulation device comprising a hand covering constituting a flexible glove made of any suitable resilient material having a palm wall and a back wall, said walls connected by a means for joining two pieces of material, said glove having one or more predetermined upward projections secured at effective working areas of the glove, said projection being made of a rubber-like material providing a means for deep and point specific pressure to affect deeper tissues, said projection attached to said glove by means providing for stationary bonding, said device being with or without one or more friction areas made of a rubber-like material having a sufficient coefficient of friction to provide a means for imparting to the recipient improved manual manipulations, said friction area attached to said glove at effective working areas by means providing for stationary bonding.
 2. The glove of claim 1 wherein said resilient material is lycra or spandex.
 3. The glove of claim 2 wherein said means for joining 2 pieces of material includes sewing.
 4. The glove of claim 3 wherein said rubber-like material of said projection is composed of polyurethane.
 5. The glove of claim 4 wherein said effective working area for said projection include the pad of digits, palm, and region of the first row of proximal phalanges.
 6. The glove of claim 5 wherein said stationary bonding for said projections and said friction area is pressure sensitive adhesion.
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7. The glove of claim 6 wherein said projection and said friction area can be of any shape, predetermined size, color, form, and texture including smooth and pimpled, and be varied on the same said glove.

8. A massage and tactile stimulation device for manual control and operation constructed of a flexible rubber-like material that contours to the anatomy of the underlying joints and part of body covered by said device, said device having one or more predetermined prominent projections made of a rubber-like material providing a means for deep and point specific pressure to affect deeper tissues of recipient of said device, said projections located at effective working areas of said device, said device being with or without one or more friction areas, said friction areas made of a rubber-like material having a sufficient coefficient of friction to provide a means for imparting to the recipient improved manual manipulations, said friction areas located at effective working areas of said device,

9. The device of claim 8 wherein said parts of body covered by said device include the hand, elbow, and foot.

10. The device of claim 9 wherein said effective working areas for said projections include the finger pads, palm, and sole of the foot.

whereby said device will impart deep pressure and improved manipulations to said recipient, and

whereby said manipulator of said device will utilize said projection and said friction area to optimize the benefits of massage and tactile stimulation to said recipient.

add 3)

add 2)